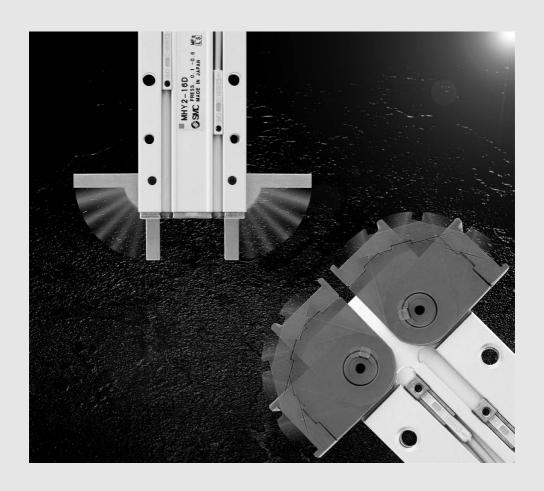
## **180° Angular Type Air Gripper**

## MHY2/MHW2 Series

ø10, ø16, ø20, ø25



## 180° Angular Type Air Gripper

Cam Type

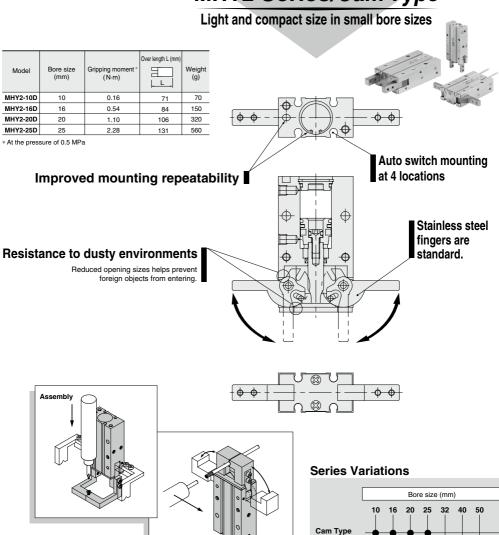
Rack & Pinion Type

## MHY2/MHW2 Series



MHY2 Series

Rack & Pinion Type MHW2 Series

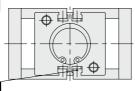


Clamping workpiece

**ØSMC** 

## MHW2 Series/Rack & Pinion Type

Unique seal design allows shorter total length construction and constant gripping force when opening and closing fingers. (PAT.PEND)



Model	Bore size (mm)	Gripping moment * (N-m)	Over length L(mm)	Weight (g)
MHW2-20D	20	0.30	68	300
MHW2-25D	25	0.73	78	510
MHW2-32D	32	1.61	93.5	905
MHW2-40D	40	3.70	117.5	2135
MHW2-50D	50	8.27	154	5100

Auto switch mounting

at 4 locations

#### Key connection is ideal for impact resistance.

Key connection between finger and shaft prevents finger angle slippage during impact.





\* At the pressure of 0.5 MPa

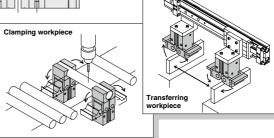


#### **Dustproof construction**

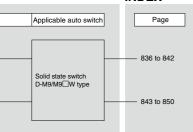
Seal arrangement protects gripper from harsh dusty environments.

**ØSMC** 

## Bearings are standard.



#### **INDEX**



## MHY2/MHW2 Series **Model Selection**

#### **Model Selection** Selection Procedure Step 2 Confirmation of gripping point Step 1 Confirmation of gripping force Step 3 Contirmation of members inertia of attachments Confirmation of moment of Step 1 Confirmation of Gripping Force Confirmation of conditions Selection of model from gripping force graph Calculation of required gripping force Example MHY2-16D Guidelines for the selection of the Workpiece mass: 0.05 kg e 0.6 MP 30 gripper with respect to workpiece mass · Although conditions differ according to the 25 workpiece shape and the coefficient of 20 friction between the attachments and the force ( 0.3 workpiece, select a model that can 15 13 provide a gripping force of 10 to 20 times 10 Gripping the workpiece mass, or more. · If high acceleration, deceleration or impact forces are encountered during motion, a 20 further margin of safety should be considered. Gripping point L (mm) Example) For setting the gripping force to be at least 20 times the work · When MHY2-16D is selected, the weight: gripping force is determined to be Required gripping force 13 N according to the gripping = 0.05 kg x 20 x 9.8 m/s<sup>2</sup> = 10 N min. point distance (L = 35 mm) and the pressure (0.4 MPa). • The gripping force is 26 times the workpiece mass and therefore Gripping point L = 35 mmsatisfies a gripping force setting value of 20 times or more. Operating pressure: 0.4 MPa **Effective Gripping Force** MHY2-10D MHY2-20D MHY2/MHW2 Series Double Acting Pressure 0.6 MPa · Indication of effective gripping force Pressure 0.6 MPa The effective gripping force shown in the graphs to 40 the right is expressed as F, which is the impellent 0.5 Ê force of one finger, when both fingers and attachments are in full contact with the workpiece 6 force ( 30 Gripping force as shown in the figure below. 0.3 Gripping f 0.3 20 0.2 0.2 2 10 0 1 30 Gripping point L (mm) Gripping point L (mm) MHY2-16D MHY2-25D Pressure 0.6 MPa Pressure 0.6 MP - 0.5 RΩ Ź 25 External grip Gripping force (N) 0.4 60 Gripping force 20

•

Gripping point L (mm)

40

20

0 30

0.1

Gripping point L (mm)

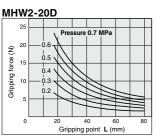
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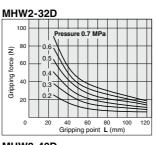
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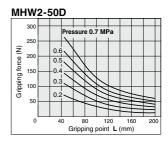
0.2 10

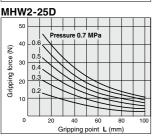
0 1

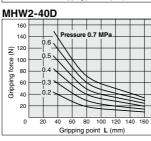
## 180° Angular Type Air Gripper MHY2/MHW2 Series



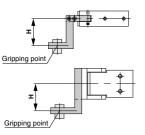


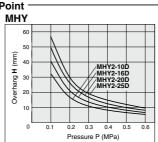


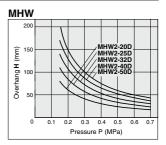




#### Step 2 Confirmation of Gripping Point







- Workpiece should be held at a point within the range of overhanging distance (H) for a given pressure indicated in the tables on the right.
- When the workpiece is held at a point outside of the recommended range for a given pressure, it may cause adverse effect on the product life.

## MHY2/MHW2 Series

## **Model Selection**

#### Step 3 Confirmation of Moment of Inertia of Attachments -



Confirm the moment of inertia for the attachment at one side. Calculate the moment of inertia for A and B separately as shown in the figures on the right.





B par

Procedure	Calculation	Calculation example				
Check the operating conditions,     dimensions of attachment, etc.	A part	Operating model: MHY2-16D Opening time: 0.15 s a = 40 (mm) b = 7 (mm) c = 8 (mm) d = 5 (mm) e = 10 (mm) f = 12 (mm)				
2. Calculate the moment of inertia of attachment.  3. Determine the allowable moment of inertia from the graph.	A part $T_1$ $T_2$ $T_3$ $T_4$ $T_4$ $T_5$ $T_5$ $T_6$	Material of attachment: Aluminum alloy (Specific gravity = 2.7) $ \begin{split} &\textbf{r}_1 = 37 \text{ (mm)} \\ &\textbf{m}_1 = 40 \times 7 \times 8 \times 2.7 \times 10^{-6} \\ &= 0.006 \text{ (kg)} \\ &\textbf{Iz}_1 = \{0.006 \times (40^2 + 7^2)/12\} \times 10^{-6} \\ &= 0.8 \times 10^{-6} \text{ (kg·m}^2) \\ &\textbf{IA} = 0.8 \times 10^{-6} + 0.006 \times 37^2 \times 10^{-6} \\ &= 9.0 \times 10^{-6} \text{ (kg·m}^2) \\ \end{split} $ $ \begin{split} &\textbf{r}_2 = 47 \text{ (mm)} \\ \end{split} $ $ \begin{split} &\textbf{m}_2 = 5 \times 10 \times 12 \times 2.7 \times 10^{-6} \\ &= 0.002 \text{ (kg)} \\ \end{split} $ $ \begin{aligned} &\textbf{Iz}_2 = \{0.002 \times (5^2 + 10^2)/12\} \times 10^{-6} \\ &= 0.02 \times 10^{-6} \text{ (kg·m}^2) \\ \end{split} $ $ \begin{aligned} &\textbf{IB} = 0.02 \times 10^{-6} \text{ (kg·m}^2) \\ &\textbf{IB} = 0.02 \times 10^{-6} \text{ (kg·m}^2) \\ \end{aligned} $ $ \begin{aligned} &\textbf{I} = 9.0 \times 10^{-6} \text{ (kg·m}^2) \\ &= 4.4 \times 10^{-6} \text{ (kg·m}^2) \\ \end{aligned} $ $ \begin{aligned} &\textbf{I} = 9.0 \times 10^{-6} + 4.4 \times 10^{-6} \\ &= 13.4 \times 10^{-6} = 0.13 \times 10^{-4} \text{ (kg·m}^2) \end{aligned} $ $ \begin{aligned} &\textbf{The moment of inertia is determined to be 0.9 \times 10^{-4} \text{ (kg·m}^2) \text{ according to the operating time (0.15 s) from the graph to the left.} $				
Confirm the moment of inertia of one attachment is within the allowable range.	Operating time (s/90°)  Moment of inertia of attachment < Allowable moment of inertia	0.13 x 10 <sup>-4</sup> (kg·m²) < 0.9 x 10 <sup>-4</sup> (kg·m²) Possible to use this model MHY2-16D completely.				

## 180° Angular Type Air Gripper MHY2/MHW2 Series

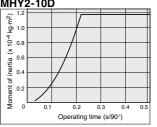
#### Symbol

Symbol	Definition	Unit
Z	Finger rotation axis	_
Z1	Axis on the center gravity of A part of attachment and parallel to Z	_
<b>Z</b> 2	Axis on the center gravity of B part of attachment and parallel to Z	_
I	Total moment of inertia for attachment	kg-m²
IZ1	Inertia moment around the Z1 axis of A part of attachment	kg·m²
IZ2	Inertia moment around the Z2 axis of B part of attachment	kg·m²

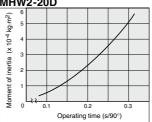
Symbol	Definition	Unit					
IA	Moment of inertia around the Z axis of A part of attachment						
ΙB	B Moment of inertia around the Z axis of B part of attachment						
m <sub>1</sub>	Weight of A part of attachment	kg					
m <sub>2</sub>	Weight of B part of attachment	kg					
ľ1	Distance between Z and Z1 axis	mm					
r <sub>2</sub>	Distance between Z and Z2 axis	mm					

#### Allowable Range of Moment of Inertia of Attachment

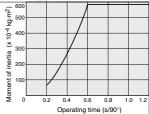
#### MHY2-10D



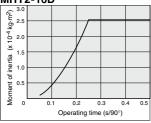




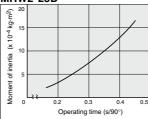
#### MHW2-50D



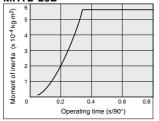




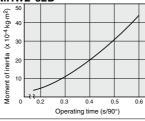
MHW2-25D



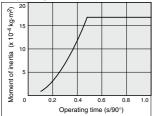
#### MHY2-20D



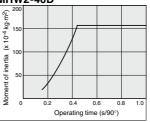
MHW2-32D



#### MHY2-25D



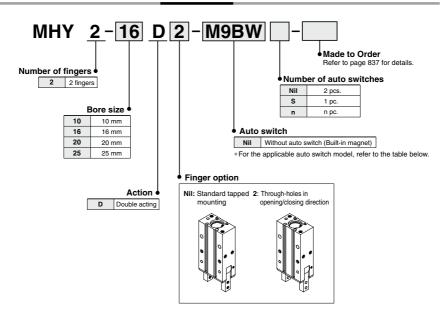
MHW2-40D





## 180° Angular Type Air Gripper **Cam Type** MHY2 Series Ø10, Ø16, Ø20, Ø25

#### **How to Order**



Applicable Auto Switches / Refer to pages 929 to 983 for further information on auto switches

					١,	oad voltag	_	Auto swit	ch model	L	ead wire I	ength (m)	)*			
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage		Electrical en	try direction	0.5	1	3	5	Pre-wired connector		cable ad	
	Turicuon	Citily	l ligiti	(Output)		DC	AC	Perpendicular	In-line	(Nil)	(M)	(L)	(Z)	COMMECTOR	10	au
			3-wire(NPN) 3-wire(PNP) 5 V, 12 V	M9NV	M9N	•	•	•	0	0	IC					
switch	_			3-wire(PNP)		5 V, 12 V	M9PV	M9P	•	•	•	0	0	circuit		
swi			2-wire		12 V	M9BV	M9B	•	•	•	0	0	_			
율	Diagnosis	Diagnosis		3-wire(NPN)	5 V. 12 V	M9N	M9NWV	M9NW	•	•	•	0	0	IC	١	
<u>a</u>	(2-color	Grommet	net Yes	3-wire(PNP)	24 V	5 V, 12 V	v, 12 v   — [	M9PWV	M9PW	•	•	•	0	0	circuit	Relay,
state	indicator)			2-wire		12 V		M9BWV	M9BW	•	•	•	0	0	_	
	Water			3-wire(NPN)		5 V 10 V	5 V 12 V I	M9NAV**	M9NA**	0	0	•	0	0	IC	
Solid	resistant (2-color			3-wire(PNP)		5 V, 12 V			M9PAV**	M9PA**	0	0	•	0	0	circuit
0,	indicator)			2-wire		12 V		M9BAV**	M9BA**	0	0	•	0	0	_	

1 m ...... M (Example) M9NWM 3 m ...... L (Example) M9NWL

5 m ...... Z (Example) M9NWZ

<sup>\*\*</sup> Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

\* I earl wire length symbols: 0.5 m ....... Nii (Example) M9NW

\* Auto switches marked with a \*O" symbol are produced upon receipt of order.

Note 1) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

## 180° Angular Type Air Gripper MHY2 Series



#### **Specifications**

Fluid	Air
Operating pressure	0.1 to 0.6 MPa
Ambient and fluid temperature	-10 to 60°C
Repeatability	±0.2 mm
Max. operating frequency	60 c.p.m.
Lubrication	Not required
Action	Double acting
Auto switch (Option) Note)	Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 929 to 983 for further information on auto switches.

#### Symbol

#### Double acting: External grip



#### Model

Model	Bore size (mm)	Effective gripping force (1) (N·m)	Opening/C (Both Opening side	closing angle sides) Closing side	Weight (2) (g)
MHY2-10D	10	0.16			70
MHY2-16D	16	0.54		_ [	150
MHY2-20D	20	1.10	180°	-3°	320
MHY2-25D	25	2.28			560

Note 1) At the pressure of 0.5 MPa Note 2) Except auto switch



#### Made to Order

Click here for details

Symbol	Specifications/Description						
-X4	Heat resistance (100°C)						
-X5	Fluororubber seal						
-X50	Without magnet						
-X53	EPDM for seals, Fluorine grease						
-X63	Fluorine grease						
-X79	Grease for food processing machines, Fluorine grease						
-X79A	Grease for food processing machines						
-X81A	Anti-corrosive treatment of finger						

- Refer to "How to Select the Applicable Model" on page 832.
- Refer to pages 832 and 833 for the details on effective holding force and allowable overhanging distance.

#### Moisture Control Tube IDK Series

When operating an actuator with a small diameter and a short stroke at a high frequency, the dew condensation (water droplet) may occur inside the piping depending on the conditions.

Simply connecting the moisture control tube to the actuator will prevent dew condensation from occurring. For details, refer to the Web Catalog.

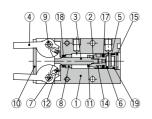


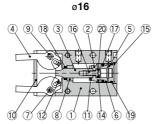
## MHY2 Series

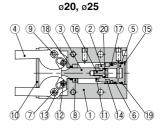
#### Construction

#### **Closed condition**

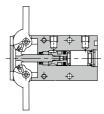
σ**1** 

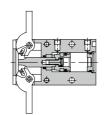


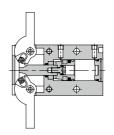




#### Open condition







#### **Component Parts**

No.	Description	Material	Note			
1	Body	Aluminum alloy	Hard anodized			
2	Piston	ø10: Stainless steel ø16 to 25: Aluminum alloy	ø16 to 25: Chromated			
3	Joint	Stainless steel	Heat treated			
4	Finger	Stainless steel	Heat treated			
5	Сар	Resin				
6	Wear ring	Resin				
7	Shaft	Stainless steel	Nitriding			
8	Bushing A	Sintered alloy steel				
9	Bushing B	Sintered alloy steel				
10	End plate	Stainless steel				

No.	Description	Material	Note
11	Bumper	Urethane rubber	
12	Needle roller	High carbon chrome bearing steel	Heat treated
13	Joint roller	Carbon steel	Nitriding
14	Rubber magnet	Synthetic rubber	
15	Type C retaining ring	Carbon steel	Phosphate coated
16	Piston bolt	Stainless steel	
17	Piston seal	NBR	
18	Rod seal	NBR	
19	Gasket	NBR	
20	Gasket	NBR	

#### Replacement Parts

Descripti	ion	MHY2-10	MHY2-16	MHY2-20	MHY2-25	Main parts	
Seal kit		MHY10-PS	MHY16-PS	MHY20-PS	MHY25-PS	<ø10> 171819	
Jeai Kit		WIII TO TO WIII TO TO		WII1120-1 3	WII1123-1 3	<ø16, ø20, ø25> ①181920	
Finger assembly	MHY2-□D	MHY-A1001	MHY-A1601	MHY-A2001	MHY-A2501	(4)(9)	
ringer assembly	MHY2-□D2	MHY-A1001-2	MHY-A1601-2	MHY-A2001-2	MHY-A2501-2		
Joint assembly		MHY-A1002	MHY-A1602	MHY-A2002	MHY-A2502	<ø10, ø16> ③12	
Joint assembly		MH1-A1002 MH1-A1602 MH1-A2002		WITT-A2302	<ø20, ø25> ③1213		
Piston assembly		MHY-A1003	MHY-A1603	MHY-A2003	MHY-A2503	<ø10> 26114	
riston assembly		MITT-A1003 MITT-A100		WII 11 - A2003	WII 11-A2303	<ø16, ø20, ø25> ②⑥⑴⑷⑥	

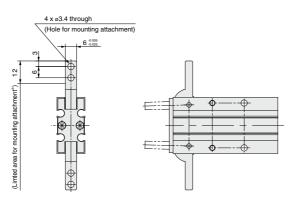
<sup>\*</sup> Order 1 piece of finger assembly per one unit.

Replacement part/grease pack part no. : MH-G04 (30 g)

#### **Dimensions**

#### MHY2-10D Pin hole positioning 2 x M3 x 0.5 thread depth 4 4 x M3 x 0.5 through (Mounting thread) (Thread for mounting attachment) 6 -0.005 4 x M3 x 0.5 thread depth 6 (Mounting thread) 2 x ø3.4 through 2 x M3 x 0.5 depth 6 (Mounting hole) (Mounting thread) (Limted area for mounting attachment\*) 24 18 23.5 ø11H9 + 0.043 depth 1.5 Positioning pin hole φ 15 47.5 58 **Auto Switch Mounting** M5 x 0.8 **Groove Dimensions** (Finger opening port) M5 x 0.8 (Finger closing port)

#### MHY2-10D2 Opening/Closing direction through-hole type

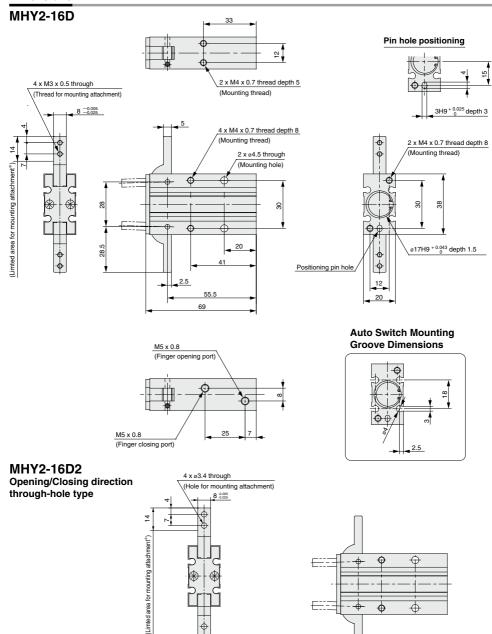


<sup>\*</sup> Do not extend the attachment from limited area for mounting to avoid interference with the attachment or main body.



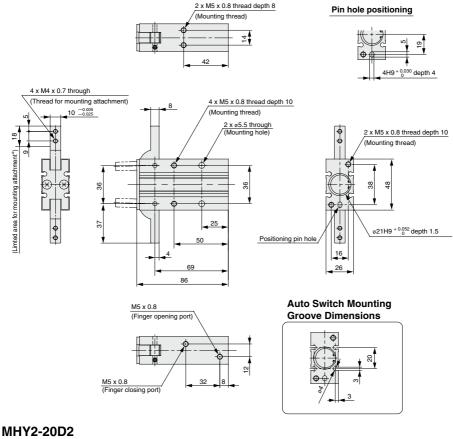
#### MHY2 Series

#### **Dimensions**

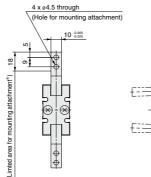


<sup>\*</sup> Do not extend the attachment from limited area for mounting to avoid interference with the attachment or main body.

#### MHY2-20D



Opening/Closing direction through-hole type



Φ

φ

ф

<sup>\*</sup> Do not extend the attachment from limited area for mounting to avoid interference with the attachment or main body.



### MHY2 Series

#### **Dimensions**

#### MHY2-25D 2 x M6 x 1 thread depth 10 Pin hole positioning (Mounting thread) Φ 50 4H9 + 0.030 depth4 4 x M5 x 0.8 through (Thread for mounting attachment) 10 4 x M6 x 1 thread depth 12 12 -0.005 (Mounting thread) 2 x ø6.6 through 4 2 x M6 x 1 thread depth 12 (Limted area for mounting attachment\*) (Mounting hole) (Mounting thread) Φ 12 42 28 ø26H9 + 0.052 depth1.5 30 ф Positioning pin hole 60 φ 18 30 107 **Auto Switch Mounting** M5 x 0.8 **Groove Dimensions** (Finger opening port) M5 x 0.8 (Finger closing port) 4 x ø5.5 through MHY2-25D2 (Hole for mounting attachment) Opening/Closing direction 12 -0.005 through-hole type (Limted area for mounting attachment\*), 22.5 12

<sup>\*</sup> Do not extend the attachment from limited area for mounting to avoid interference with the attachment or main body.

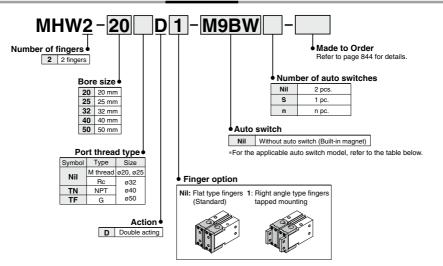


# 180° Angular Type Air Gripper Rack & Pinion Type

# MHW2 Series

Ø20, Ø25, Ø32, Ø40, Ø50





Applicable Auto Switches / Refer to pages 929 to 983 for further information on auto switches

					Load voltage		_	Auto swit	ch model	L	ead wire I	ength (m)	)*		Applicable	
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)			Electrical entry direction		try direction	0.5	1	3	5	Pre-wired connector		cable ad
			ligit.	(Output)		DC	AC	Perpendicular	In-line	(Nil)	(M)	(L)	(Z)	COMMECTOR	10	au
				3-wire(NPN)		5 V, 12 V		M9NV	M9N	•	•	•	0	0	IC	
둥	_			3-wire(PNP)				M9PV	M9P	•	•	•	0	0	circuit	
switch				2-wire			12 V	M9BV	M9B	•	•	•	0	0		
d of o	Diagnosis		ommet Yes	3-wire(NPN)		24 V 5 V, 12 V —	,	M9NWV	M9NW	•	•	•	0	0	IC	<b>.</b>
a	(2-color	Grommet		3-wire(PNP)	24 V		M9PWV	M9PW	•	•	•	0	0	circuit	Relay,	
state	indicator)			2-wire			12 V	M9BWV	M9BW	•	•	•	0	0	_	- = 0
Solid	Water			3-wire(NPN)	5.1/	5 V. 12 V		M9NAV**	M9NA**	0	0	•	0	0	IC	
So	resistant (2-color indicator)			3-wire(PNP)		5 V, 12 V	<b>'</b>	M9PAV**	M9PA**	0	0	•	0	0	circuit	
				2-wire		12 V		M9BAV**	M9BA**	0	0	•	0	0	_	

- \*\* Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.
- \* Lead wire length symbols: 0.5 m ······· Nil (Example) M9NW \* Auto switches marked with a "O" symbol are produced upon receipt of order.

1 m ······· M (Example) M9NWM 3 m ······ L (Example) M9NWL 5 m ····· Z (Example) M9NWZ

Note 1) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

Note 2) When ordering the air gripper with the auto switch, the auto switch mounting bracket is included.

When ordering the auto switch separately, the auto switch mounting bracket (BMG2-012) is required.

#### MHW2 Series



#### **Specifications**

Fluid	Air
Operating pressure	0.15 to 0.7 MPa
Ambient and fluid temperature	−10 to 60°C
Repeatability	±0.2 mm
Max. operating frequency	ø20, 25: 60 c.p.m. ø32 to 50: 30 c.p.m.
Lubrication	Not required
Action	Double acting
Auto switch (Option) Note)	Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 929 to 983 for further information on auto switches.

#### Symbol

#### Double acting: External grip



#### Made to Order Click here for details

Symbol	Specifications/Description
-X4	Heat resistance
-X5	Fluororubber seal
-X50	Without magnet
-X53	EPDM for seals, Fluorine grease
-X63	Fluorine grease
-X79	Grease for food processing machines, Fluorine grease
-X79A	Grease for food processing machines

#### Model

Model	Bore size	Effective gripping force	Opening angle (Both sides)		Weight (2)
	(mm)	(N·m)	Opening	Closing	(g)
MHW2-20D	20	0.30		-5°	300
MHW2-20D1	20	0.30		-3	320
MHW2-25D	25	0.73	180°	-6°	510
MHW2-25D1					540
MHW2-32D		1.61		-5°	910
MHW2-32D1	32				950
MHW2-40D	40	40 3.70		-5°	2140
MHW2-40D1	40			-5	2270
MHW2-50D		0.07		-4°	5100
MHW2-50D1	50	8.27			5350

Note 1) At the pressure of 0.5 MPa

Note 2) Except auto switch

- Refer to "How to Select the Applicable Model" on page 832
- Refer to pages 832 and 833 for the details on effective holding force and allowable overhanging distance.

#### **⚠** Precautions

Be sure to read this before handling the products.

Refer to page 7 for safety instructions and pages 14 to 22 for air gripper and auto switch precautions.

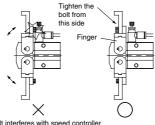
#### Mounting

MHW

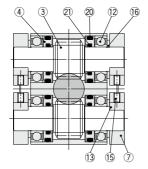
844

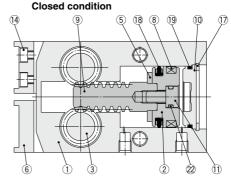
## **△ Warning**

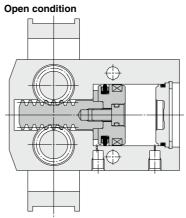
When using right angle finger tap mounting type, monitor the interference of the bolt with the speed controller.



#### Construction







#### **Component Parts**

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston	Aluminum alloy	Hard anodized
3	Pinion gear	Carbon steel	Heat treated
4	Seal cover	Brass	
5	Bumper	Urethane rubber	
6	Finger (A)	Carbon steel	Heat treatment/Special treatment
7	Finger (B)	Carbon steel	Heat treatment/Special treatment
8	Rubber magnet	Synthetic rubber	
9	Rack	Carbon steel	Heat treatment/Special treatment
8	Rubber magnet	Synthetic rubber	·

No.	Description	Material	Note
10	Com	ø20, 25: Resin	
	Сар	ø32 to 50: Aluminum alloy	Hard anodized
11	Piston bolt	Stainless steel	
12	Ball bearing	Carbon steel	Schield type
13	Key	ey Carbon steel	
14	Hexagon socket head bolt	Carbon steel	Zinc chromated
15	Hexagon socket cap screw	Carbon steel	Zinc chromated
16	Type C retaining ring for axis	Carbon steel	Phosphate coated
17	Type C retaining ring for hole	Carbon steel	Phosphate coated

#### **Replacement Parts**

Description		MHW2-20	MHW2-25	MHW2-32	MHW2-40	MHW2-50	Main parts
Seal kit		MHW20-PS	MHW25-PS	MHW32-PS	MHW40-PS	MHW50-PS	1819202122
Piston assembly		MHW-A2001	MHW-A2501	MHW-A3201	MHW-A4001	MHW-A5001	25891122
Finance constable	MHW2-□D	MHW-A2002	MHW-A2502	MHW-A3202	MHW-A4002	MHW-A5002	6(7)(3(14)15
Finger assembly	MHW2-□D1	MHW-A2002-1	MHW-A2502-1	MHW-A3202-1	MHW-A4002-1	MHW-A5002-1	67/13(14(15)
Finger A assembly	MHW2-□D	MHW-A2006	MHW-A2506	MHW-A3206	MHW-A4006	MHW-A5006	614
Finger C assembly	MHW2-□D1	MHW-A2006-1	MHW-A2506-1	MHW-A3206-1	MHW-A4006-1	MHW-A5006-1	614
Finger B assembly		MHW-A2007	MHW-A2507	MHW-A3207	MHW-A4007	MHW-A5007	7(3(5)

<sup>\*</sup> Please order 1 piece finger assembly per one unit.

Replacement part/grease pack part no. : ø20, ø25, ø32 : GR-S-010(10 g) ø40, 50 : GR-S-020(20 g)

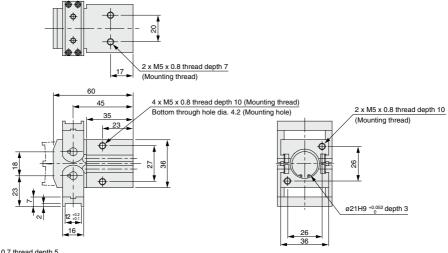


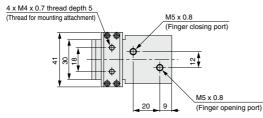
## MHW2 Series

#### **Dimensions**

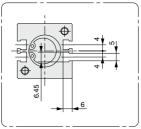
#### MHW2-20D

Flat finger type (Standard)



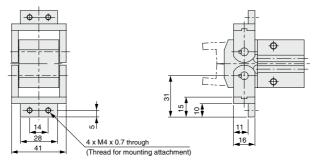


#### Auto Switch Mounting Groove Dimensions



#### MHW2-20D1

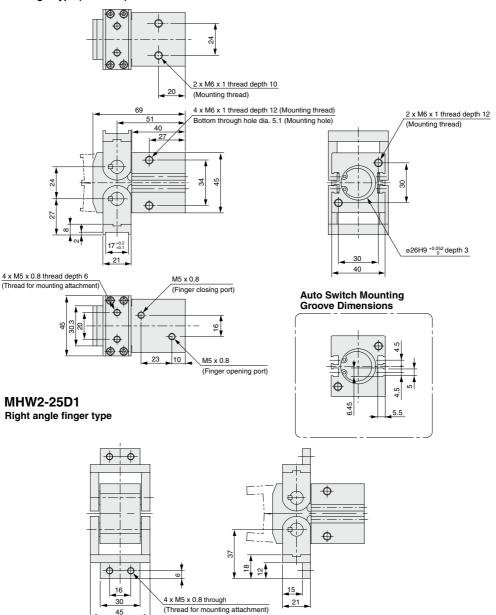
Right angle finger type



#### **Dimensions**

#### MHW2-25D

Flat finger type (Standard)

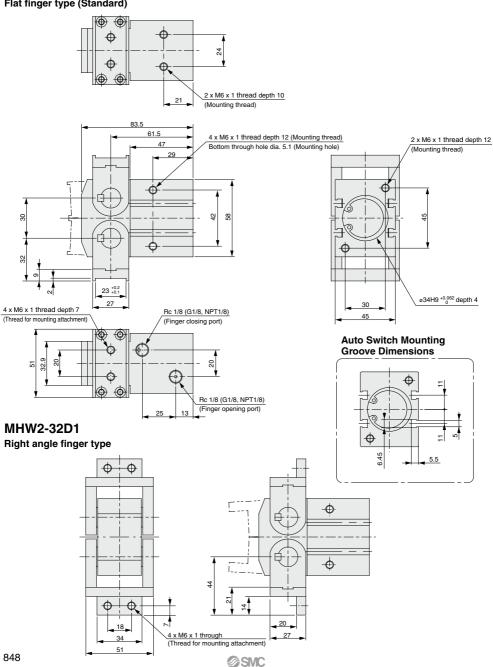


## MHW2 Series

#### **Dimensions**

#### MHW2-32D

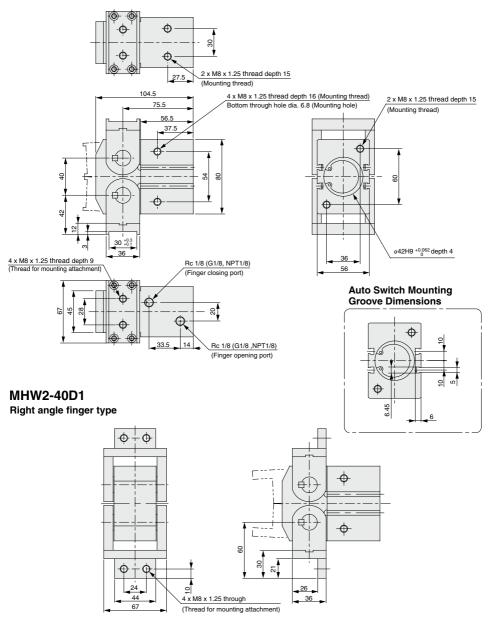
Flat finger type (Standard)



#### **Dimensions**

#### MHW2-40D

Flat finger type (Standard)

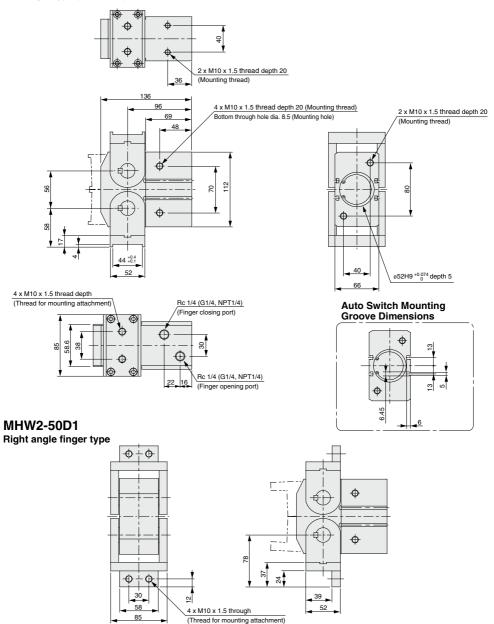


### MHW2 Series

#### **Dimensions**

#### MHW2-50D

Flat finger type (Standard)



**SMC** 

850

# MHY2/MHW2 Series Auto Switch Installation Examples and Mounting Positions

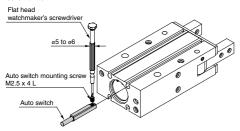
Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

<b>Detection when Grippin</b>	ng Exterior of Workpiece	
Detection example	Confirmation of the fingers in reset position	2. Confirmation of work held
Position to be detected	Position of fingers fully opened	Position when gripping a workpiece
Operation of auto switch	Auto Switch turned ON when fingers return. (Light ON)	Auto Switch turned ON when gripping a workpiece. (Light ON)
How to determine auto switch installation position	Step 1) Completely open the fingers.	Step 1) Position fingers for gripping a workpiece.
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it.
	Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out.  Step 5) Move the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates.	Position where light turns ON  Position to be secured
	Position where light turns ON  Position to be secured	<b>⊕</b> ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩ ₩

#### MHY2 Series

#### **Auto Switch Mounting**

To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



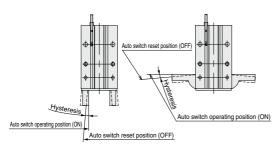
Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw.

Also, tighten with a torque of about 0.05 to 0.15 N⋅m, or about 0.05 to 0.10 N⋅m for D-M9□A(V).

\* Refer to the page 936 for the details on "Auto Switches Connection and Example".

#### **Auto Switch Hysteresis**

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



		D-M9□(V) D-M9□W(V)/M9A(V)
MHY2	Finger fully closed	2°
-10D	Finger fully open	4°
MHY2	Finger fully closed	2°
-16D	Finger fully open	3°
MHY2	Finger fully closed	2°
-20D	Finger fully open	3°
MHY2	Finger fully closed	1°
-25D	Finger fully open	2°

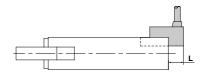
#### Protrusion of Auto Switch from Edge of Body

The projection of an auto switch from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

Note) 2-color indicator type and perpendicular entry type protrude in the direction of the lead wire entry.



#### When auto switch D-M9□ is used



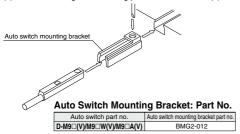
When auto switch D-M9□V is used

## Max. Protrusion of Auto Switch

from Edge of Body (L) (mm) Auto switch Protrusion model In-line Perpendicular In-line Perpendicular Finger D-M9□ D-M9□V D-M9□A D-M9□AV grippe D-M9□W D-M9□WV model Open MHY2-10D 3 1 5 3 Open MHY2-16D Closed 3 1 5 3 Open MHY2-20D 3 Closed 1 Open MHY2-25D Closed

#### **Auto Switch Mounting**

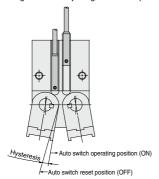
- Insert the auto switch bracket into the installation groove of the gripper as shown below and roughly set it.
- (2) Insert the auto switch into the auto switch bracket installation groove.
- (3) After confirming the detecting position, tighten the set screws (M2.5) attached to the auto switch and set it.
- (4) Be sure to change the detecting position in the state of (2).



Note) Use a screwdriver with a grip diameter of 5 to 6 mm to tighten the set screws (M2.5). The tightening torque should be 0.5 to 1 N·m. As a rule, it should be turned about 90° beyond the point at which tightening can be felt.

#### **Auto Switch Hysteresis**

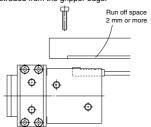
Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



Auto switch model Air gripper model	Max. hysteresis (Max. value)  D-M9□(V)  D-M9□W(V)  D-M9□A(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°

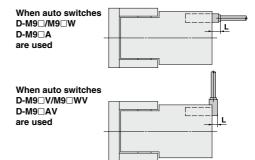
#### **Handling of Mounting Brackets**

When auto switch is set on mounting side as shown below, allow at least 2 mm run off space on mounting late since the auto switch is protruded from the gripper edge.



#### Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully closed) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.



Max. Protrusion of Auto Switch

irom Ea	rom Eage of Body (L) (mm				
Auto switch		Protrusion (mm)			
Air gripper Finge	model	In-line electrical e	ntry type	Perpendicular electrial entry type	
model pr	osition	D-M9□/M9□W	M9□A	D-M9□V/M9□WV	M9□AV
MHW2-20D	Open	_	_	_	
WITW2-20D	Closed	7	9	5	7
MHW2-25D	Open				l—
WITW2-25D	Closed	7	9	5	7
MHW2-32D	Open	_	_	_	
WITW2-32D	Closed	4	6	2	4
MHW2-40D	Open		_	_	_
WITW2-40D	Closed	3	5	1	3
MHW2-50D	Open				l <del>-</del>
IVITIVY 2-50D	Closed	1	3	_	1



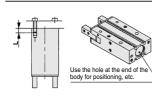
# MHY2/MHW2 Series Specific Product Precautions 1

Be sure to read this before handling the products. Refer to page 7 for safety instructions and pages 14 to 22 for air gripper and auto switch precautions.

#### Mounting Air Grippers/MHY2 Series

Possible to mount from 3 directions.

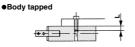
## Axial Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.88	6
MHY2-16D	M4 x 0.7	2.1	8
MHY2-20D	M5 x 0.8	4.3	10
MHY2-25D	M6 x 1	7.4	12

Model	Bore(mm)	Hole depth (mm)
MHY2-10D	ø11H9 +0.043	1.5
MHY2-16D	ø17H9 +0.043	1.5
MHY2-20D	ø21H9 +0.052	1.5
MILINO OFF	-OCLIO #0.052	4.5

## Lateral mounting (Body Tapped, Body through-hole)



Model		Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
	MHY2-10D	M3 x 0.5	0.88	6
	MHY2-16D	M4 x 0.7	2.1	8
	MHY2-20D	M5 x 0.8	4.3	10
	MHY2-25D	M6 x 1	7.4	12

#### ●Body through-hole



Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D	M3 x 0.5	0.88
MHY2-16D	M4 x 0.7	2.1
MHY2-20D	M5 x 0.8	4.3
MHY2-25D	M6 x 1	7.4

## Vertical Mounting (Body Tapped)



Model		Applicable bolts	Max. tightening torque (N-m)	Max. screw-in depth (Lmm)
	MHY2-10D	M3 x 0.5	0.59	4
	MHY2-16D	M4 x 0.7	1.3	5
	MHY2-20D	M5 x 0.8	3.3	8
	MHY2-25D	M6 x 1	5.9	10

#### How to Mount the Attachment to the Finger



- (1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- (2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model Applicable bolts		Max. tightening torque (N·m)
MHY2-10D MHY2-16D	M3 x 0.5	0.59
MHY2-20D	M4 x 0.7	1.4
MHY2-25D	M5 x 0.8	2.8

#### **Operating Environment/ MHY2 Series**

#### 

Use caution for the anti-corrosiveness of finger guide section.

Martensitic stainless steel is used for the finger. However, be aware that its anti-corrosion performance is inferior to austenitic stainless steel. In particular, the finger might be rusted in an environment where water droplets are adhered to it due to dew condensation.





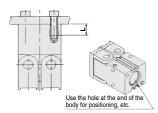
# MHY2/MHW2 Series Specific Product Precautions 2

Be sure to read this before handling the products. Refer to page 7 for safety instructions and pages 14 to 22 for air gripper and auto switch precautions.

#### Mounting Air Grippers/MHW2 Series

Possible to mount from 3 directions.

## Axial Mounting (Body Tapped)

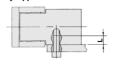


Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

Model	Bore(mm)	Hole depth (mm)
MHW2-20D	ø21H9 +0.052	3
MHW2-25D	ø26H9 +0.052	3
MHW2-32D	ø34H9 +0.062	4
MHW2-40D	ø42H9 +0.062	4
MHW2-50D	ø52H9 +0.074	-

## Lateral mounting (Body Tapped, Body through-hole)

#### ●Body tapped



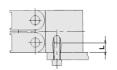
Model	Applicable bolts	Max. tightening torque (N-m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	16
MHW2-50D	M10 x 1.5	37.2	20

#### ●Body through-hole



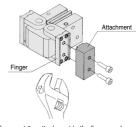
Model	Applicable bolts	Max. tightening torque (N·m)
MHW2-20D	M4 x 0.7	2.1
MHW2-25D	M5 x 0.8	4.3
MHW2-32D	M5 x 0.8	4.3
MHW2-40D	M6 x 1	7.4
MHW2-50D	M8 x 1.25	17.7

## Vertical Mounting (Body Tapped)



Model	Model Applicable bolts Max. tightening torque (N·m)		Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	2.9	7
MHW2-25D	M6 x 1	5.9	10
MHW2-32D	M6 x 1	5.9	10
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

#### How to Mount the Attachment to the Finger



- (1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- (2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Applicable bolts	Max. tightening torque (N·m)		
MHW2-20D	M4 x 0.7	1.4		
MHW2-25D	M5 x 0.8	2.5		
MHW2-32D	M6 x 1	4.1		
MHW2-40D	M8 x 1.25	10.6		
MHW2-50D	M10 x 1.5	24.5		